# STAT 237 <br> Approximate Inference via Sampling 

March 23-28, 2022

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## Outline

Prediction and Expected Value

## Sampling to Approximate Expected Values

Sampling Methods
Inverse CDF Method
Rejection Sampling

Markov Chain Monte Carlo

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## The (Prior) Predictive Distribution

- We used the product rule and marginalization to show that

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p(x)=\int_{\operatorname{Range}(\theta)} p(\theta) p(x \mid \theta) d \theta
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which is a weighted average of $p(x \mid \theta)$ values for each mu, weighted by the prior, $p(\theta)$, on $\theta$

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- In other words, we can write

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where the expectation is taken with respect to the prior

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- This works when we have multiple observations as well

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- Note that both of these are instances of taking the expected value of a function of $\theta$, because in $p(x \mid \theta), x$ acts as a constant


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- That is, if $x=1$, we are asking for $\mathbb{E}[\mu]$, and if $x=0$ we are asking for $\mathbb{E}[1-\mu]$
- If $p(\mu)$ is a $\operatorname{Beta}(a, b)$ distribution, then

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\mathbb{E}[\mu]=\frac{a}{a+b} \quad \mathbb{E}[1-\mu]=\frac{b}{a+b}
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- By the same logic

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p\left(x_{\text {new }} \mid x_{\text {old }}\right)=\int_{\operatorname{Range}(\theta)} p\left(\theta \mid x_{\text {old }}\right) p\left(x_{\text {new }} \mid \theta, x_{\text {old }}\right) d \theta
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## Beyond Means and Conjugate Priors

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## Beyond Means and Conjugate Priors

- When we have a Beta posterior and the quantity we want the expected value of is something simple like $\mu$ itself, we can get these values analytically
- What do we do if the function of $\mu$ we care about is more complicated, and/or our posterior distribution isn't part of a recognizable family?
- For example, we might have reason to use a non-conjugate prior, or we might have more than one parameter, such that the joint posterior over the parameters is difficult to work with


## The Law of Large Numbers

If we generate $S$ independent observations according to the distribution of $\theta$, and apply the function $f$ to each observation, then the "sample" mean of the $f(\theta)$ s "approaches" $\mathbb{E}[f(\theta)]$ as $S$ increases:

$$
\frac{1}{S} \sum_{s=1}^{S} f\left(\theta^{(s)}\right) \rightarrow \mathbb{E}[f(\theta)] \text { as } S \rightarrow \infty
$$

## Notation Note:

It's conventional to use the superscript with parentheses to denote a simulated value - this isn't an exponent.

$$
\theta^{(s)}:=\text { the } s^{\text {th }} \text { simulated value of } \theta
$$

## Simulation Demonstration of the LLN



Figure: Simulation of $\bar{\theta}=\frac{1}{S} \sum_{s=1}^{S} \theta^{(s)}$, for various $S$, where $\theta^{(s)} \ldots \theta^{(1000)}$ are sampled independently from a $\mathcal{N}(0,1)$ distribution

## Sampling from the Posterior

- Therefore, provided we can sample from our posterior distribution, $p\left(\theta \mid x_{1}, \ldots, x_{N}\right)$, we can estimate the expected value of various functions of $\theta$
- For example, if we want $\mathbb{E}\left[p\left(x_{\text {new }} \mid \mu\right)\right]$, we could approximate it via

$$
\mathbb{E}\left[p\left(x_{\text {new }} \mid \mu\right)\right] \approx \frac{1}{S} \sum_{s=1}^{S} \mathbb{E}\left[p\left(x_{\text {new }} \mid \mu^{(s)}\right)\right]
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- Solution: Generate $U \sim \operatorname{Unif}(0,1)$, and return $F^{-1}(U)$
- As long as $F^{-1}$ is defined, this will produce samples distributed as $X$


## Inverse CDF Method



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Hence we can sample $X$ values by generating $U \sim \operatorname{Unif}(0,1)$ and returning

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x=-\frac{\log (1-U)}{\lambda}
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## Example: Exponential Distribution




## Discrete Case

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- Sample $U \sim \operatorname{Unif}(0,1)$ and return

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- l.e., find the two $x$ values on either side of the "gap" enclosing $U$, and choose the upper one.


## Example: Binomial Distribution




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- Idea: find a similar distribution, $q(x)$ to sample from, and "filter" the results using a " $p$-shaped" filter.


## Rejection Sampling




## Rejection Sampling Algorithm

1. Choose a "proposal density" $q$ "similar" to target $p$.
2. Find a scaling constant $k$ so that $k \cdot q(x)$ is at or above $p(x)$ for all $x$.
3. Sample $x^{*}$ from $q$
4. Accept $x^{*}$ with probability $\frac{p(x)}{k \cdot q(x)}$; otherwise, reject, and try again until acceptance.

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- E.g., detection limit $\theta$ with a uniform likelihood and a Gamma prior:

$$
\begin{aligned}
& p(\theta)=\frac{b^{a}}{\Gamma(a)} \theta^{a-1} e^{-b \theta}, \quad \theta>0 \\
& p(y \mid \theta)=\theta^{-1} \quad \theta \geq y \\
& p(\theta \mid y) \propto \frac{b^{a}}{\Gamma(a)} \theta^{a-1-1} e^{-b \theta}, \quad \theta \geq y
\end{aligned}
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1. $p(x)=c \cdot \frac{b^{a}}{\Gamma(a)} \theta^{a-1-1} e^{-b \theta}, \quad \theta \geq y$
2. Choose $q(x)=\frac{b^{a}}{\Gamma(a)} \theta^{a-1-1} e^{-b \theta}, \quad \theta \geq 0$
3. Then $p(x) / c q(x)=1$ for all $\theta \geq 0$, and 0 otherwise.
4. So, generate $x$ from $q(x)$, and accept if $\theta \geq y$; reject otherwise.

## Drawbacks of Rejection Sampling

1. For high-dimensional distributions, it's very hard to find a good proposal.
2. It can be quite difficult to find a valid rescaling constant, without making the rejection probability unacceptably high.

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- Idea: Use the current value to "seed" the next one


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- In other words, $p^{*}\left(\theta^{(s)} \mid \theta^{(s-1)}\right)$ preserves $p(\theta)$ once it "finds" it


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- What is the conditional distribution, $p^{*}\left(\theta^{(s)} \mid \theta^{(s-1)}\right)$ ?


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(ii) If heads, set $\theta^{(s)}=\theta^{(s-1)}+1$ (wrapping around so that 6 goes to 1)
(iii) If tails, set $\theta^{(s)}=\theta^{(s-1)}-1$ (wrapping around so that 1 goes to 6)

- What is the conditional distribution, $p^{*}\left(\theta^{(s)} \mid \theta^{(s-1)}\right)$ ?
- What is the marginal distribution, $p^{*}\left(\theta^{(s)}\right)$ ?


## Random Walks

-What is the conditional distribution, $p^{*}\left(\theta^{(s)} \mid \theta^{(s-1)}\right)$ ?

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- Depends on the marginal distribution of $\theta^{(s-1)}$


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- Answer: 0 , except if $\theta^{(s-1)}=3$ or 5 . In that case, $1 / 2$

$$
\begin{aligned}
p^{*}\left(\theta^{(s)}=4\right) & =\frac{1}{6}\left(0+0+\frac{1}{2}+0+\frac{1}{2}+0\right) \\
& =\frac{1}{6}
\end{aligned}
$$

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- The same logic holds for other values
- So, once $\theta^{(s-1)}$ has the right distribution, our algorithm preserves it
- But if we could set $\theta^{(0)}$ to the right distribution, we wouldn't be doing this...
-What happens if $\theta^{(0)}=1$ with probability 1 ?


## Random Walks

- The distribution of $\theta^{(1)}$ is then

$$
p^{*}\left(\theta^{(s)} \mid \theta^{(s-1)}\right)= \begin{cases}\frac{1}{2} & \theta(s)=2 \\ \frac{1}{2} & \theta(s)=6 \\ 0 & \text { otherwise }\end{cases}
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- The distribution of $\theta^{(2)}$ is

$$
p^{*}\left(\theta^{(2)}\right)= \begin{cases}\frac{1}{2} \cdot \frac{1}{2} & \theta^{(s)}=5 \\ \frac{1}{2} \cdot \frac{1}{2}+\frac{1}{2} \cdot \frac{1}{2} & \theta^{(s)}=1 \\ \frac{1}{2} \cdot \frac{1}{2} & \theta^{(s)}=3\end{cases}
$$

## Random Walks

- The distribution of $\theta^{(3)}$ is then

$$
p^{*}\left(\theta^{(3)}\right)= \begin{cases}\frac{1}{4} \cdot \frac{1}{2}+\frac{1}{2} \cdot \frac{1}{2} & \theta(s)=4 \\ \frac{1}{4} \cdot \frac{1}{2}+\frac{1}{2} \cdot \frac{1}{2} & \theta(s)=6 \\ \frac{1}{2} \cdot \frac{1}{2}+\frac{1}{4} \cdot \frac{1}{2} & \theta(s)=2\end{cases}
$$

